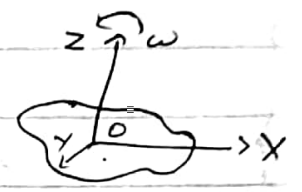


\* Moment of Inertia -

Moment of Inertia, about a given axis plays the same part in rotational motion about that axis as the mass of a body does in translational motion.

"Mass is taken to be a measure of Inertia for linear or translatory motion."

$$I = \sum_i m_i r_i^2 = M K^2$$



M → total mass of the body

K → Effective distance of its particle from the axis of rotation.

If body does not consists discrete particles then,

$$I = \int r^2 dm = M K^2$$

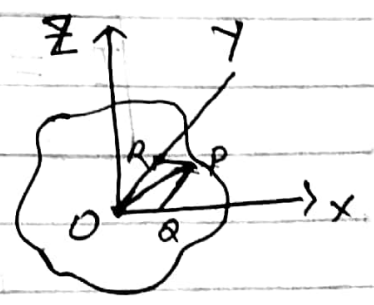
dm → mass of the infinitesimal small element of the body at a distance r from the axis.

# General Theorems on Moment of Inertia -

(1) Theorem of  $I_{z}$  axis

Applicable to plane bodies

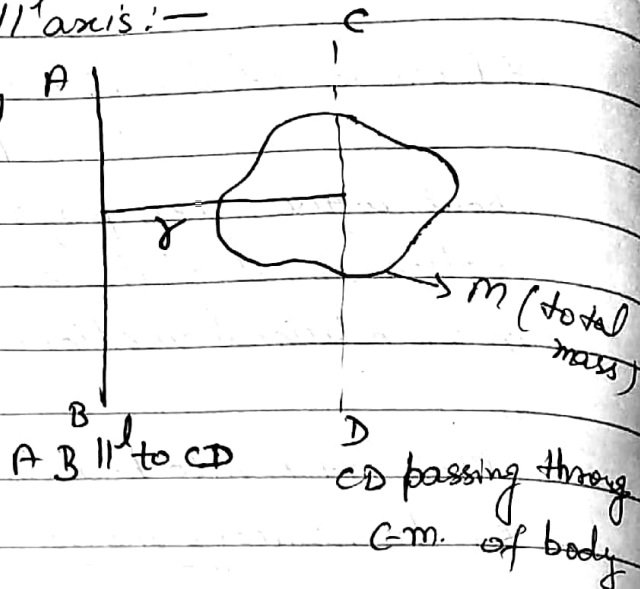
X and Y axis Chosen ~~in~~ in plane of body and Z-axis  $I_{z}$  to this plane.



$$I_z = I_x + I_y$$

(2) Theorem of  $11^{\text{th}}$  axis:—

$$I = I_{cm} + mY^2$$



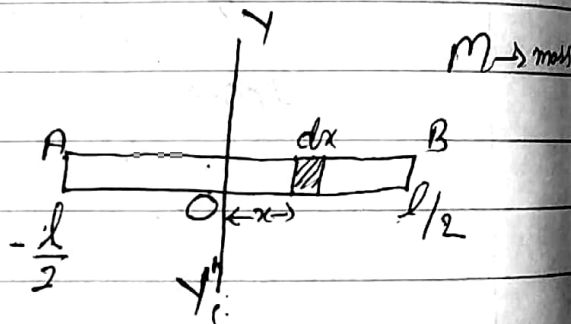
\* Particular Cases of Moment of Inertia—

[1] M.I. of a Uniform rod of length 'l'

(i) About an axis passing through its Centre and  $\perp$  to its length

$$I = \int_{-l/2}^{l/2} \frac{m}{l} dx \cdot x^2$$

$$= 2 \int_0^{l/2} \frac{m}{l} x^2 dx$$



$$I = \frac{ml^2}{12}$$

(ii) About an axis passing through its one end and  $\perp$  to its length.

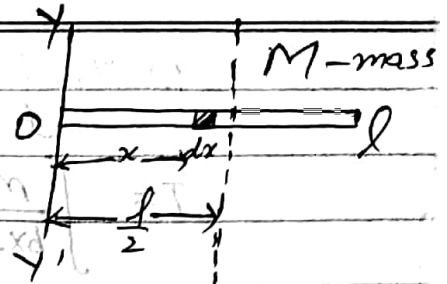
$$I = I_{cm} + Mx^2$$

$$I = \frac{Ml^2}{12} + M\left(\frac{l}{2}\right)^2$$

$$I = \frac{Ml^2}{3}$$

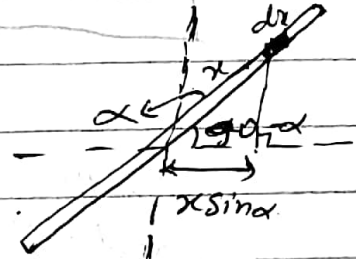
or

$$I = \int_0^l \frac{m}{l} \cdot dx \cdot x^2 = \frac{Ml^2}{3}$$

(Passing through  
Centre of mass)

(iii) If rod is aligned at angle  $\alpha$  from the axis of rotation -

$$I = \int_{-l/2}^{l/2} \frac{m}{l} dx (x \sin \alpha)^2$$



axis of rotation

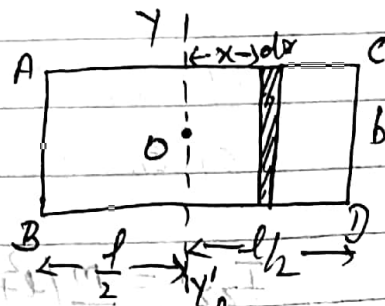
$$I = \frac{Ml^2}{12} \sin^2 \alpha$$

[2] Moment of Inertia of a rectangular lamina,

(i) about an axis through its centre and  $\parallel$  to its one side

$$I = \int_{-l/2}^{l/2} \left( \frac{m}{lx} \cdot b dx \right) \cdot x^2$$

$$I = \frac{ml^2}{12}$$

( $\parallel$  to AB and CD)

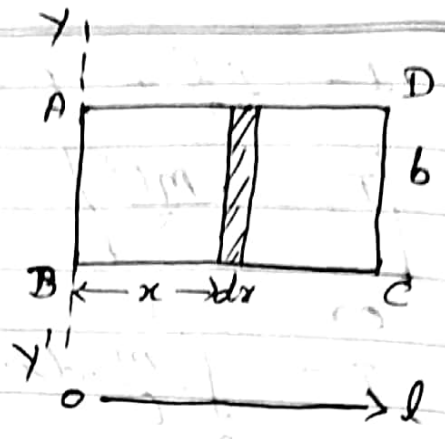
If  $YOY'$  is  $\parallel$  to AC & BD then  $I = \frac{mb^2}{12}$

(ii) About one side

$$I = \int_0^l \frac{m}{bx \cdot l} \cdot b dx \cdot x^2$$

$$= \int_0^l \frac{m}{l} \cdot x^2 dx$$

$$I = \frac{ml^2}{3}$$



or

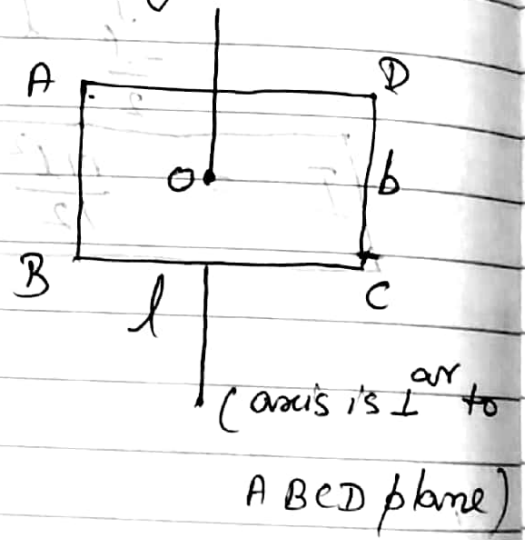
$$I = \frac{ml^2}{12} + m\left(\frac{l}{2}\right)^2$$

(iii) About an axis passing through its centre and  $\perp$  to its plane

Theorem of  $\perp$  axis  
 $I_z = I_x + I_y$

$$I = \frac{ml^2}{12} + \frac{mb^2}{12}$$

$$I = \frac{1}{12} m(l^2 + b^2)$$

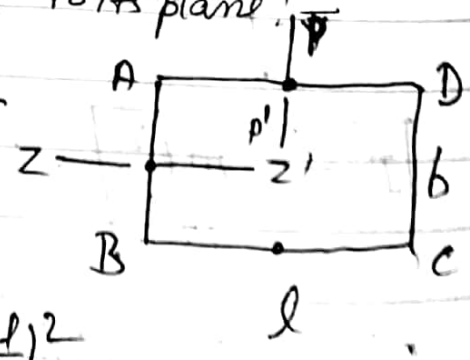


(iv) About an axis passing through the mid point of one side and  $\perp$  to its plane

$$I_{zz'} = \frac{m}{12}(l^2 + b^2) + m\left(\frac{b}{2}\right)^2$$

and

$$I_{pp'} = \frac{m}{12}(l^2 + b^2) + m\left(\frac{l}{2}\right)^2$$



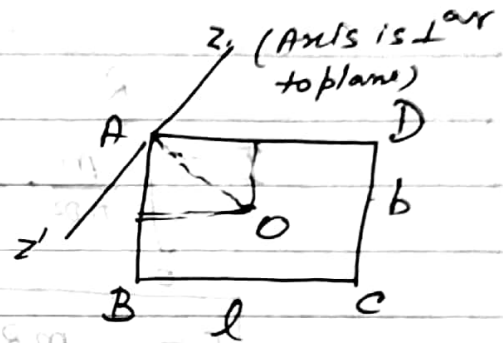
passing through

→ Axis  $zz'$  is  $\perp^{\text{or}}$  to ABCD plane and  $\odot$  mid point of AB it may be CD also

→ Similarly  $pp'$  is  $\perp^{\text{or}}$  to plane and passing through mid point of AD may be BC also.

$$(V) \therefore AO^2 = \left(\frac{l}{2}\right)^2 + \left(\frac{b}{2}\right)^2$$

$$= \frac{l^2 + b^2}{4}$$



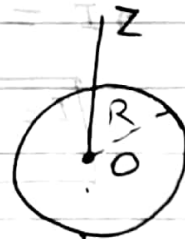
$$I = I_{\text{cm}} + m(AO)^2$$

$$I = \frac{m(l^2 + b^2)}{12} + \frac{m(l^2 + b^2)}{4}$$

[3] Moment of Inertia of a hoop or a thin circular ring

(i) About an axis passing through its centre and  $\perp^{\text{or}}$  to its plane.

$$I = mR^2$$



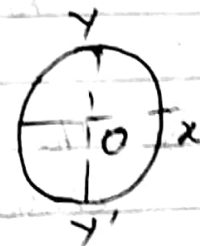
$z'$  ( $\perp^{\text{or}}$  to plane)

(ii) About its diameter:-

By theorem

$$I_x + I_y = I_z \quad \text{--- (1)}$$

$$\therefore I_x = I_y$$



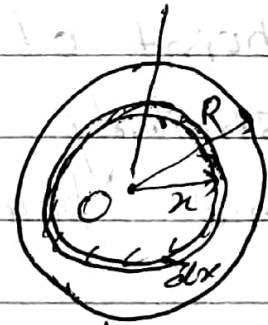
$$I_x = I_y = \frac{I_z}{2} = \frac{mR^2}{2}$$

[4] Moment of Inertia of a circular lamina or disc

(i) About an axis through centre and  $\perp$  to plane

$$I = \int_0^R \frac{m}{\pi R^2} \cdot 2\pi x dx \cdot x^2$$

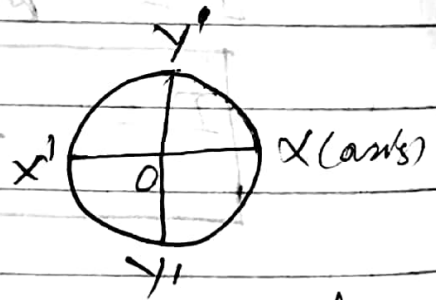
$$I = \frac{mR^2}{2}$$



Axis is through centre O &  $\perp$  to plane

(ii) About a diameter:-

$$I_x = I_y = I \text{ (M.I. about any diameter is same)}$$



about an axis

$$I_x + I_y = I_z$$

$$2I = \frac{1}{2} mR^2$$

$$I = \frac{mR^2}{4}$$

$I_z$  is  $mR^2 \perp$  to plane & passing through O